

TITLE

Repeated horizontal jumping is a feasible exercise countermeasure for microgravity

AUTHOR

Cleather, Daniel J.; Price, Phil D. B.; Kennett, John E.

JOURNAL

Microgravity Science and Technology

DATE DEPOSITED

24 November 2022

This version available at

<https://research.stmarys.ac.uk/id/eprint/5549/>

COPYRIGHT AND REUSE

Open Research Archive makes this work available, in accordance with publisher policies, for research purposes.

VERSIONS

The version presented here may differ from the published version. For citation purposes, please consult the published version for pagination, volume/issue and date of publication.

1 **Author's Accepted Version**

2
3 Cleather, D.J., Price, P.D.B. & Kennett, J.E. Repeated Horizontal Jumping is a Feasible
4 Exercise Countermeasure for Microgravity. *Microgravity Sci. Technol.* **34**, 68 (2022).
5 <https://doi.org/10.1007/s12217-022-09987-8>
6
7
8
9

10 **Repeated horizontal jumping is a feasible exercise countermeasure for**
11 **microgravity**

12 Daniel J Cleather^{1,2*}, Phil DB Price¹ and John E Kennett³

13 ¹ St Mary's University, Waldegrave Road, Twickenham, TW1 4SX, UK

14 ² Institute for Globally Distributed Open Research and Education (IGDORE)

15 ³ Physical Mind London, Teddington, TW11 8HH, UK

16 * Corresponding author: daniel.cleather@stmarys.ac.uk; +420 775 255 586

17 **Keywords:** jump sled; amputee; para-astronaut; space exploration; HIFIm

18 Word count: 2900

19 Figures: 6

20 Tables: 1

21

22 **ABSTRACT**

23 Objectives: Astronauts who spend prolonged time in microgravity on the International Space
24 Station can experience a significant reduction in physical fitness. Jumping exercises represent
25 a potential solution to this problem as the European Space Agency has demonstrated that the
26 deconditioning effect of long-term bed-rest can be countered with around four minutes per day
27 of jumping. The purpose of this study was to evaluate if repeated jumping is possible in
28 microgravity and if the transmission of impact forces and vibration to the aircraft can be
29 minimised.

30 Methods: Five subjects performed repeated jumping on a custom jump sled both in
31 microgravity during a parabolic flight campaign and in normal gravitational conditions. Forces
32 expressed by the user and transmitted to the aircraft were quantified using a bespoke
33 instrumentation system.

34 Results: These results show, for the first time, that repeated horizontal jumping is possible in
35 microgravity, and that force transmission can be minimised by using a custom supine jump
36 sled. The peak effective ground reaction force experienced by the user was sensitive to both
37 the style of jumping used and resistance employed.

38 Conclusion: These results open the door to the next generation of exercise countermeasures for
39 deep space exploration. In particular, we have qualified the High Frequency Impulse for
40 Microgravity (HIFIm) exercise device to a Technology Readiness Level of 6 making it a
41 leading candidate to replace the Advanced Resistive Exercise Device (ARED) which has been
42 in service since 2009.

43

44

45 **INTRODUCTION**

46 A key challenge to the success of space exploration missions is the fact that humans experience
47 significant deconditioning when spending a prolonged period of time in microgravity [1].
48 These effects are wide ranging and include a loss of bone mineral density (BMD), muscle
49 strength, aerobic fitness and musculoskeletal function [2–4]. For this reason, astronauts spend
50 a considerable amount of time on ‘countermeasure exercise’ that is designed to mitigate these
51 decrements in physical fitness. In particular, up to 25% of the working day on the International
52 Space Station (ISS) is spent on exercise countermeasures [5]. Despite this, it is still common
53 that astronauts returning from ISS after long duration missions exhibit substantial
54 deconditioning.

55 Recently, interest in the use of jumping as an exercise countermeasure has increased. This is
56 predominantly driven by the success of a European Space Agency (ESA) study that
57 demonstrated that the deconditioning effect of long-term bed-rest could be mitigated with just
58 3-4 minutes of repeated jumping activity daily using a horizontal ‘jump sled’ that provides a
59 resistance that returns the user to the take-off surface after each jump [6–8]. Jumping is thought
60 to be effective because it is a form of impact exercise that requires high levels of muscular
61 activation [9]. In addition, the resistive element of training on the jump sled apparatus is also
62 beneficial in preserving bone density [10,11] and muscle strength [12,13], making this form of
63 exercise highly effective.

64 Jumping could therefore be a potent strategy to increase the effectiveness of countermeasure
65 training while reducing its time demands. Of course, there is clearly a technical challenge to be
66 overcome in order to jump repeatedly in the absence of gravity. One solution to this is the use
67 of the aforementioned jump sleds which provide a resistance to movement that compensates
68 for the lack of gravity and that return the user to the ‘ground’ (or jump board) after each jump.

69 Such a jump sled was employed in the ESA bed-rest study [6,14]. However, it has yet to be
70 demonstrated if such jump sleds actually work in microgravity and whether repeated jumping
71 is feasible. A second major challenge to the realisation of repeated jumping as an exercise
72 countermeasure is the need to ensure that the impact forces and vibration created during
73 exercise are not transmitted to the spacecraft. This is important both from a safety perspective
74 but also because space habitats like ISS are laboratories with experiments that are sensitive to
75 external forces.

76 The High Frequency Impulse for Microgravity (HIFIm) jump sled has been designed to address
77 the unique challenges of jumping in microgravity. In particular, the sled is comprised of upper
78 and lower carriages of equal mass, that move equal and opposite to one another during jumping,
79 and which should minimise force transmission. The purpose of this study was thus to evaluate
80 whether HIFIm could be used to facilitate repeated jumping in microgravity during parabolic
81 flight. The study had two aims. The first was to establish the feasibility of jumping in
82 microgravity using HIFIm. The second was to test the hypothesis that the design of HIFIm
83 would minimise force transmission to the aircraft.

84 **MATERIALS AND METHODS**

85 This experiment was a feasibility study to evaluate whether HIFIm can be used to facilitate
86 repeated horizontal jumping in microgravity. Testing was performed from 22nd to 28th October
87 2021, during the 77th European Space Agency Parabolic Flight Campaign in Bordeaux. Five
88 subjects performed repeated jumping exercise on HIFIm in both microgravity and normal
89 gravitational conditions.

90

91

92 **Subjects**

93 The subjects recruited for this study were prospectively chosen to ensure a range of body sizes
94 and sexes that are reflective of potential users (i.e. astronauts; Table 1). All subjects had
95 previous experience of jumping on HIFIm prior to the study and took part in further
96 familiarisation practice prior to data collection. Ethical approval for this study was provided by
97 St Mary's University, Twickenham, United Kingdom and the Comité de Protection des
98 Personnes Nord-Ouest II, Amiens, France (21.01095.000005). The study was conducted in
99 accordance with the Declaration of Helsinki (seventh revision) and all subjects provided
100 informed written consent prior to experimentation.

101 Table 1. Subject characteristics.

Subject	Sex	Age (years)	Height (m)	Mass (kg)	Spring Resistance (No. of Springs)		
					Set 1	Set 2	Set 3
1	F	35	1.62	56	3	4	2
2	M	52	1.80	94	2	3	2
3	M	51	1.70	84	3	4	2
4	F	30	1.65	63	4	5	3
5	M	35	1.87	91	4	5	3

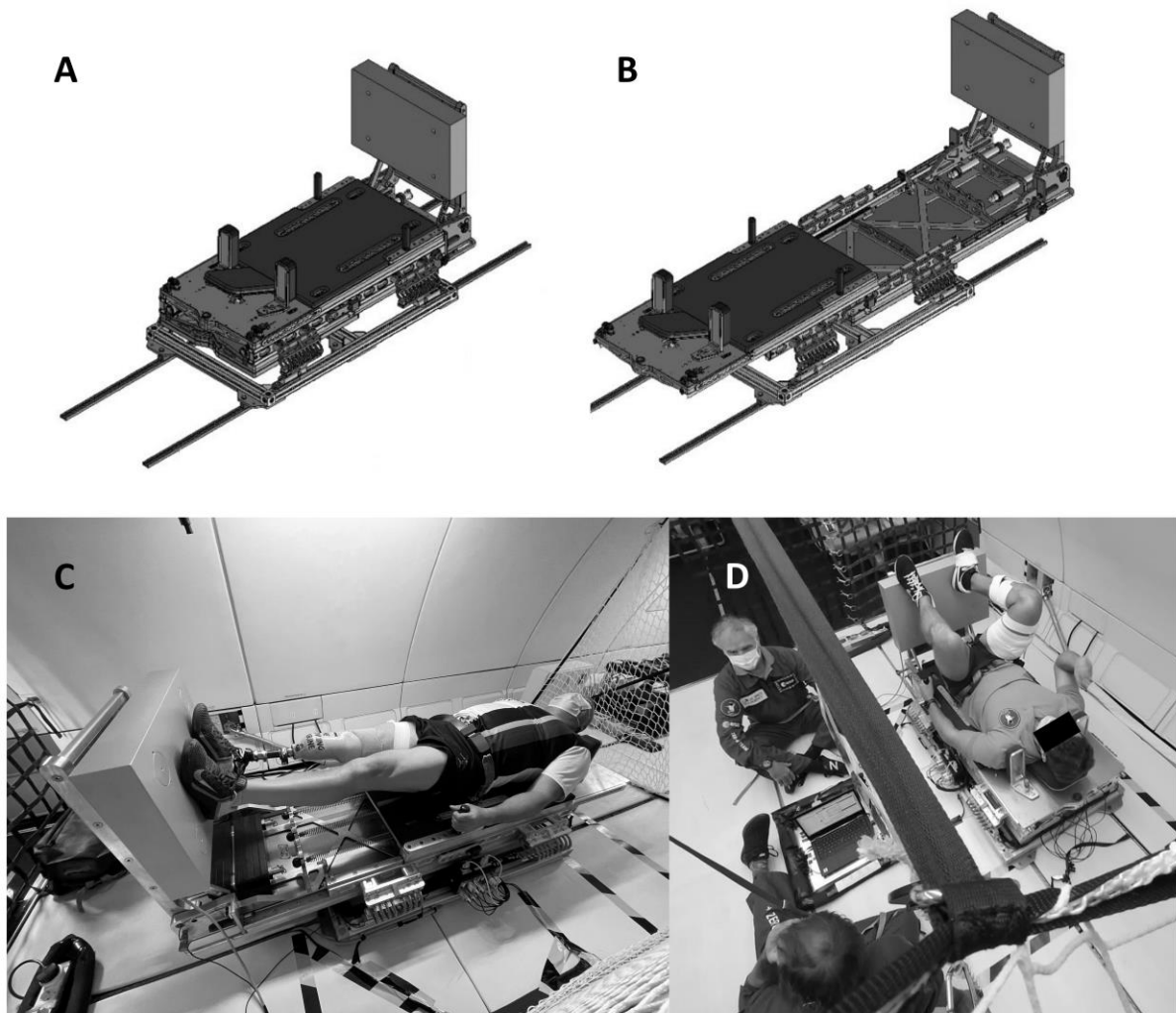
102

103 **Instrumentation**

104 High Frequency Impulse for Microgravity (HIFIm; Figure 1) is a prototype system designed to
105 facilitate a range of exercise countermeasures in microgravity. HIFIm is sled-based and
106 comprised of upper and lower moving carriages that are mechanically connected via a rack and
107 pinion such that the movement of the carriages is constrained to be equal and opposite (Figure
108 1). Resistance to movement is provided by high tensile springs that link the upper and lower
109 carriages. The mass of the user is borne by the upper carriage and the mass of the lower carriage
110 is equalized to the mass of the upper carriage system by the addition of balance weights. The

111 user jumps by pushing against the force plate that is mounted on the jump plate of the lower
112 carriage.

113



114

115 Figure 1. HIFIm. A) closed position; B) open position; C) side view during 1g testing; D) view
116 from above during microgravity testing.

117

118 A bespoke instrumentation system was developed to capture the forces expressed during the
119 operation of HIFIm and the muscular activity of the user. This included a Kistler

120 Multicomponent Force Plate (Type 9281E; Kistler Group, Eulachstrasse 22, 8408 Winterthur,
121 Switzerland), 4 load cells (Strainsense Load Beam Series LBS; Strainsense Ltd, Old Stratford
122 Business Park, Falcon Drive, Old Stratford, Milton Keynes, MK19 6FG, United Kingdom) to
123 measure the force between HIFIm and the aircraft and 3 wireless electromyography (EMG)
124 sensors (Cometa Wave Plus; Cometa srl, Via Verdi 24, 20080 Cisliano MI, Italy). All of the
125 data collection equipment was wired into a single National Instruments data logger (NI cDAQ
126 9171 with a NI 9205 voltage input module; National Instruments Corp, 11500 North Mopac
127 Expressway, Austin, TX 78759-3504, USA) to ensure the synchronous collection of data. A
128 custom LabView NXG 5.0 (also National Instruments Corp) script was developed to manage
129 the instrumentation and to display and record all data. Data was collected at 1000 Hz. The
130 EMG signals were processed in real-time in LabView every 0.1s. The signal was first filtered
131 using a 2nd order, Butterworth band pass filter (10 – 500 Hz), rectified, and then passed through
132 a 2nd order, Butterworth low pass filter (10 Hz) to obtain the linear envelope.

133 **Procedure**

134 Prior to each flight, each subject was equipped with EMG electrodes on the right leg, following
135 SENIAM guidelines (<http://www.seniam.org/>). Firstly, the skin was prepared by shaving and
136 then cleaning with an alcohol wipe. Electrodes were then placed on the gluteus maximus
137 (halfway between the sacral vertebrae and the greater trochanter), vastus lateralis (two thirds
138 of the way from the anterior spina iliaca superior to the lateral side of the pelvis) and on the
139 most prominent bulge of the medial gastrocnemius. Maximum voluntary contractions (MVCs)
140 were then performed against the manual resistance of a member of the research team.

141 Each parabolic flight comprised 31 parabolas. The first parabola was used to take baseline
142 readings from HIFIm with the user remaining still and not in contact with the force plate.
143 Following this, parabolas were performed in sets of 5, with a new parabola starting every 3

144 minutes. There was a 5 minute break between each set of 5 parabolas and a break of 8 minutes
145 after the first 15 parabolas. The microgravity phase of each parabola was of approximately 22
146 seconds duration. The campaign consisted of 3 flights. Each subject exercised on HIFIm for 15
147 parabolas and so 2 subjects were tested on each flight except for the final flight where only 1
148 subject was tested. The 8 minute break after 15 parabolas was used for the change-over of
149 subjects and the 5 minute breaks between sets of 5 parabolas were used to change the spring
150 resistance.

151 A moderate spring resistance was used for the first set of parabolas which was used to accustom
152 the user to jumping in microgravity (Table 1). The appropriate spring resistance was
153 determined during familiarisation based upon the clinical judgment of the inventor of HIFIm
154 (JEK). During the first parabola the user simply squatted in order to get used to moving on
155 HIFIm in microgravity. The next 2 parabolas were used to practise normal bilateral jumping,
156 with the user instructed to take their time getting used to the environment. By the fourth
157 parabola all subjects were comfortable moving on HIFIm and were able to jump normally –
158 generally subjects were asked to complete 10 jumps within the microgravity phase of a
159 parabola. The spring resistance was increased for the second set of 5 parabolas. Finally, the
160 spring resistance was decreased for the third set which was used to experiment with different
161 jumping styles. In this final set, subjects performed 1 set of bilateral jumping, 2 sets of bilateral
162 rebound jumps (i.e. jumping with a stiffer landing, involving less knee flexion and more
163 emphasis on using the ankle as the means of propulsion) and 2 sets of unilateral jumps using
164 the right leg.

165 An audio recording that replicated the cabin announcements made during the flight was
166 created to simulate the timings of the parabolic flight. Each subject took part in a simulated

167 parabolic flight on the ground prior to taking part in an actual flight. This ground-based testing
168 was performed within the plane using all of the protocols described above.

169 **Statistical Analysis**

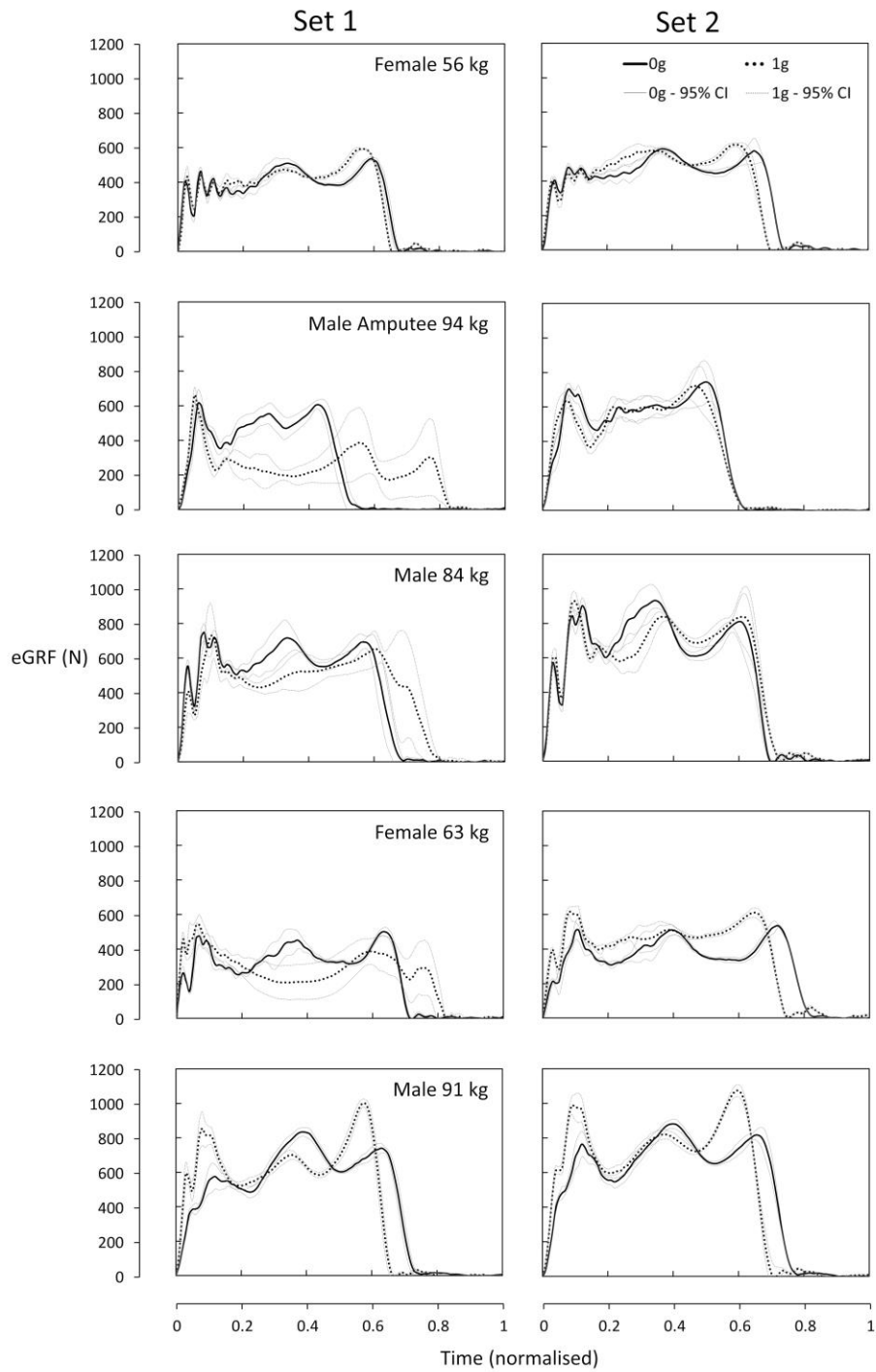
170 The fourth, fifth and sixth jumps from each parabola were chosen for analysis to ensure that
171 the analysed jumps were performed in microgravity after the user had established their jumping
172 rhythm. Jumps were chosen such that there were representative jumps for each spring
173 resistance and jump style. The start of each jump was identified as being the frame when the
174 user first made contact with the force plate and ended at the frame that preceded the next contact
175 with the first plate. Each jump was time normalised to a nominal time period of 1 unit, and then
176 spline interpolated in GNU Octave (www.gnu.org) to find values of the variables of interest
177 (effective ground reaction force from the force plate, eGRF; force between HIFIm and the
178 aircraft measured from the load cells; EMG activations normalised to MVCs) at regular
179 intervals of 0.01 unit [15,16]. The mean and standard deviations at each time point were taken
180 to produce composite representative time series and 95% confidence intervals for each jump
181 condition and variable of interest. In particular, we present representative curves for set 1
182 (lighter spring resistance), set 2 (heavier spring resistance) and for the three different jump
183 styles used in set 3. A multivariate repeated measures analysis of variance performed in IBM
184 SPSS Statistics (version 26; IBM, Armonk, NY) was used to test for differences in peak
185 muscular activations between gravitational conditions and set number.

186 **RESULTS**

187 All subjects used HIFIm without difficulty in microgravity and generally reported that jumping
188 in microgravity felt similar to normal gravity. There was a high degree of similarity between
189 the force-time profiles of repeated jumping in microgravity and normal gravity (Figure 2). The
190 exception to this is for the male amputee in 1g, who despite his familiarity with HIFIm, was

191 very cautious when first jumping on HIFIm within the experimental environment (i.e. with
192 HIFIm actually loaded onto the aeroplane). Mean peak eGRFs ranged between 600 and 1000N.
193 Mean peak eGRFs were higher when the spring resistance was greater (i.e. in set 2 compared
194 to set 1). The relative length of the flight phase of the jump was greater when spring resistance
195 was lower. The forces between HIFIm and the aircraft were greatly reduced in microgravity
196 and were negligible for much of the jump cycle (Figure 3). The peak force was subsequent to
197 the participant first making impact with the force plate, and in microgravity was typically
198 around 500N.

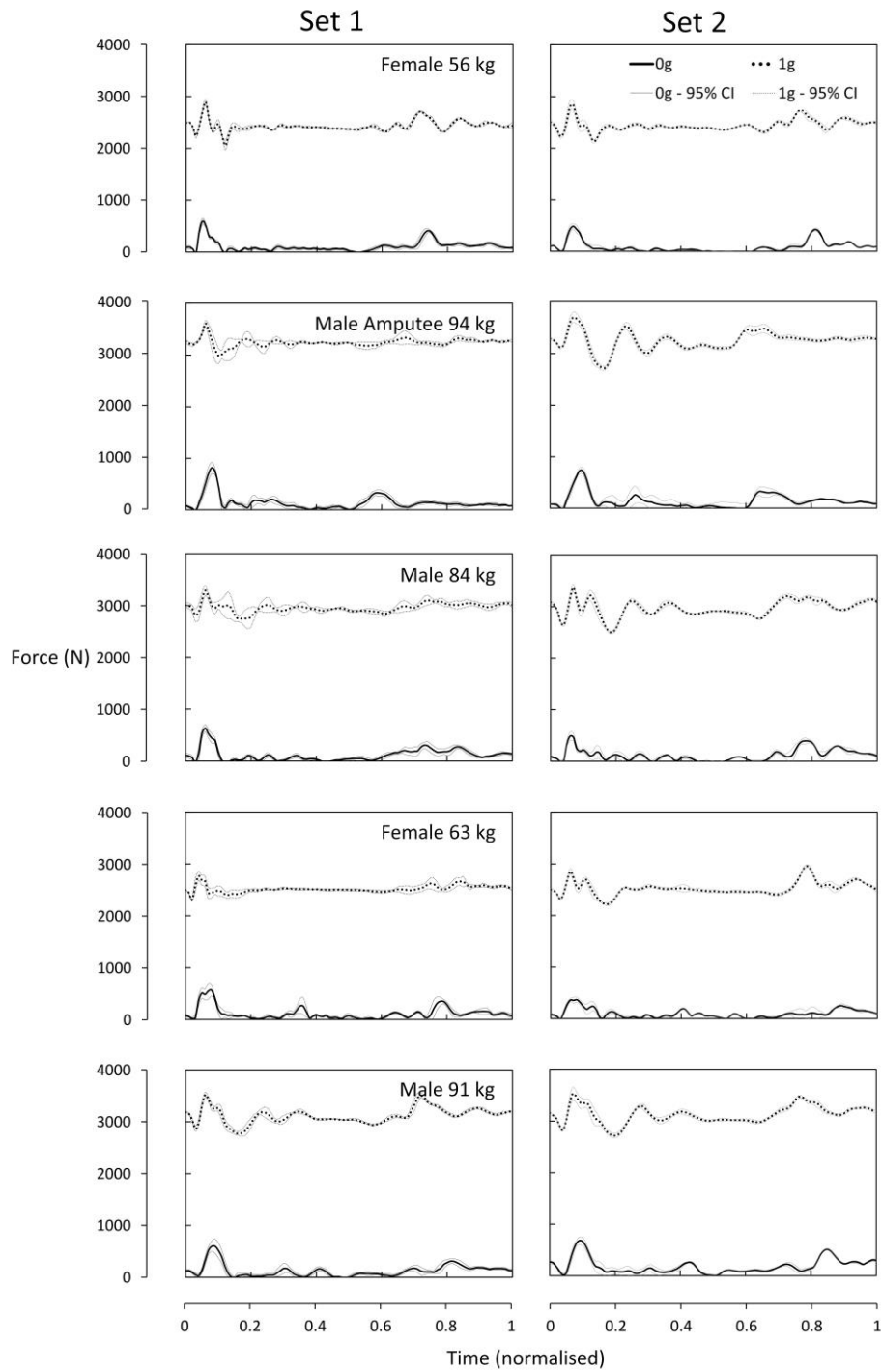
199



200

201 Figure 2. Mean effective ground reaction forces (eGRF) expressed during repeated horizontal
 202 jumping on HIFIm in normal (1g) and microgravity (0g). Mean is taken over a number of single
 203 jump cycles. Set 1 jumps are performed against a lighter resistance than set 2 (CI = confidence
 204 interval).

24/11/2022

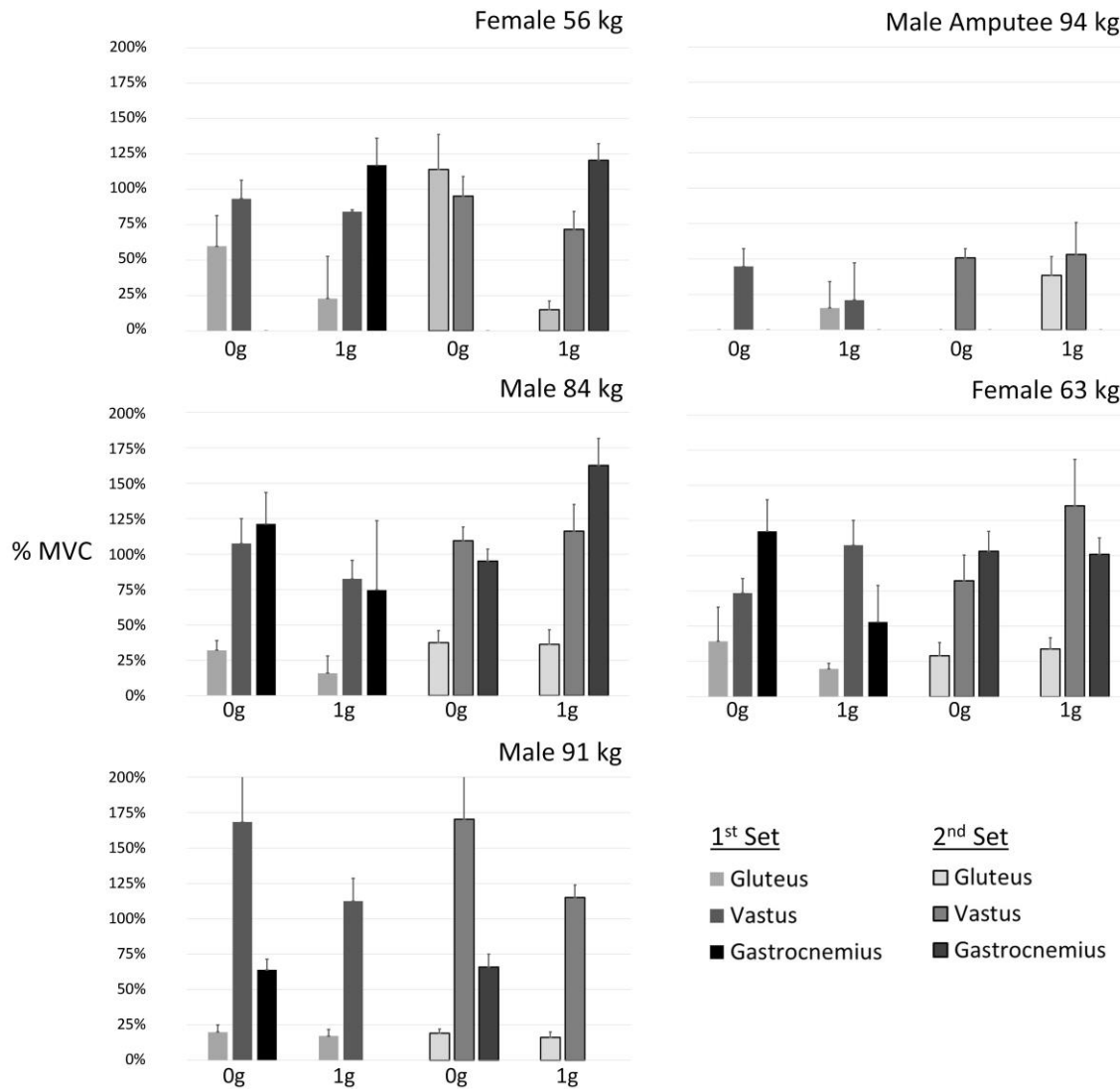


205

206 Figure 3. Mean forces between HIFIm and aircraft during repeated horizontal jumping on
 207 HIFIm in normal (1g) and microgravity (0g). Mean is taken over a number of single jump
 208 cycles. Set 1 jumps are performed against a lighter resistance than set 2 (CI = confidence
 209 interval).

210 Muscular activation of the lower limb was substantial during jumping on HIFIm in both
211 microgravity and normal gravity (Figure 4). There were no statistically significant differences
212 between the muscular activations seen in microgravity or normal gravity or between set 1 and
213 set 2. There was considerable variation in the peak muscular activities but some broad trends
214 were observed. In particular, mean peak activity of the vastus and gastrocnemius was typically
215 at, or in excess of, 100% of the MVC value. Conversely, mean peak activity of the glutes was
216 typically between 25% and 50% of MVC.

217



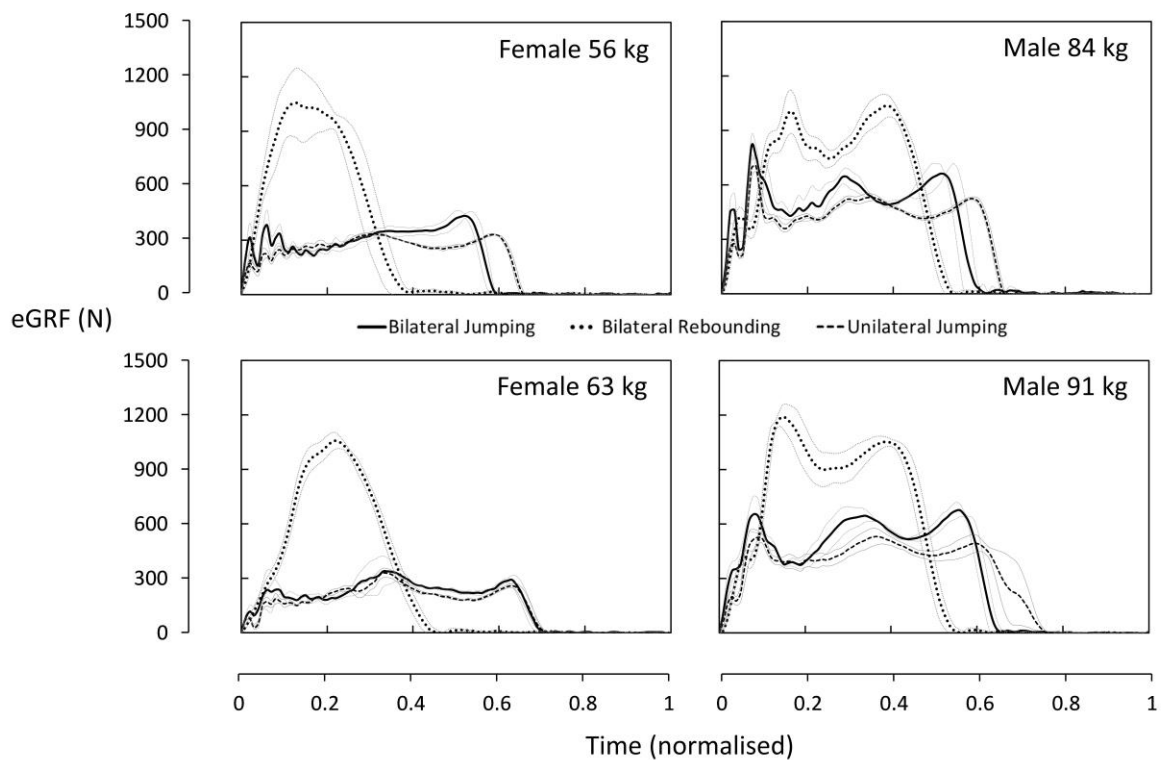
218

219 Figure 4. Mean peak muscular activity as a percentage of maximal voluntary contraction
 220 (MVC) during repeated horizontal jumping on HIFIm in normal (1g) and microgravity (0g).
 221 Mean is taken over a number of single jump cycles. Set 1 jumps are performed against a lighter
 222 resistance than set 2. Error bars indicate the 95% confidence interval. Missing data is due to
 223 equipment failure during data collection.

224

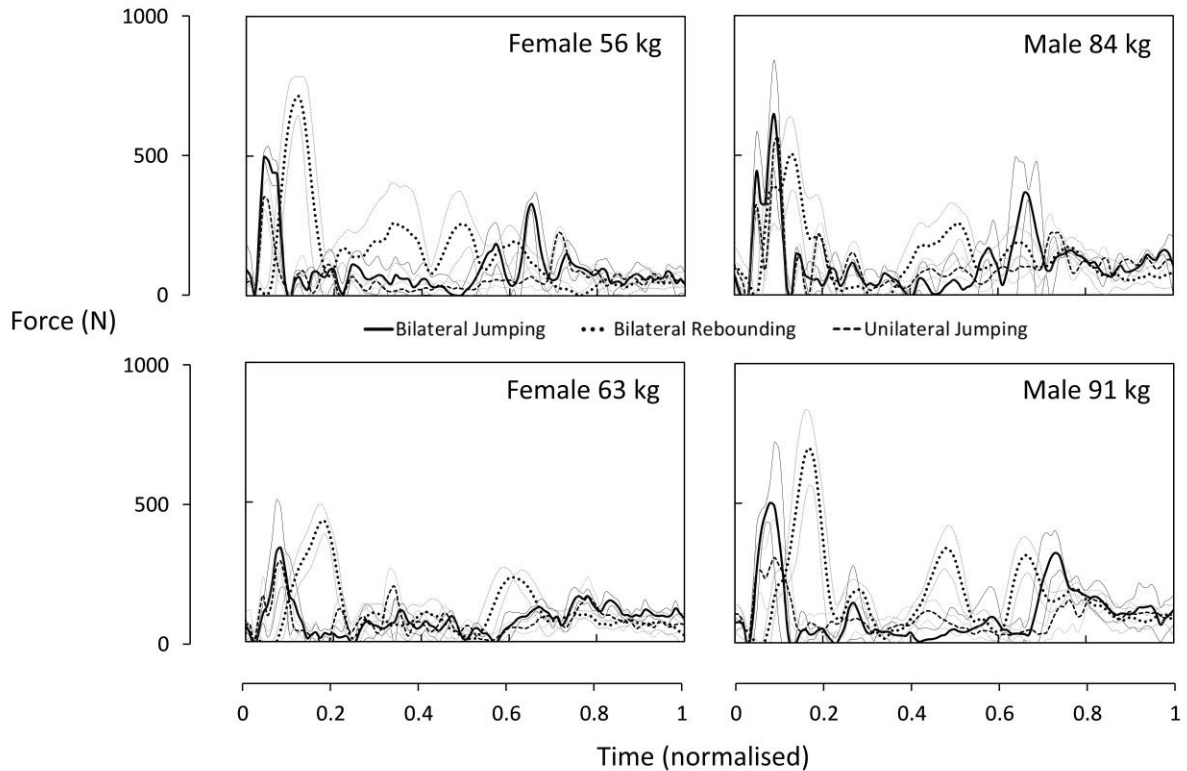
225 The mean peak eGRFs were very sensitive to the jumping style employed. In particular, the
 226 stiffest jump style (bilateral rebounding) produced the greatest mean peak eGRFs of between

227 1000 and 1200N (Figure 5). This was significantly greater than the mean peak eGRFs of 300
 228 to 800N during bilateral ‘normal’ jumping that were seen at the same spring tension. In
 229 addition, the force-time curves for unilateral jumping were notably similar to those seen during
 230 bilateral jumping. There was a weaker relationship between jumping style and mean peak force
 231 between HIFIm and the aircraft (Figure 6). For 3 of the 4 subjects, unilateral jumping produced
 232 the lowest mean peak forces whereas rebound jumping produced the highest forces.



233

234 Figure 5. Mean effective ground reaction forces (eGRF) expressed during repeated horizontal
 235 jumping on HIFIm in microgravity for 3 different styles of jumping. Mean is taken over a
 236 number of single jump cycles. Lighter lines indicate the 95% confidence interval.



237

238 Figure 6. Mean forces between HIFIm and aircraft during repeated horizontal jumping on
 239 HIFIm in microgravity for 3 different styles of jumping. Mean is taken over a number of single
 240 jump cycles. Lighter lines indicate the 95% confidence interval.

241

242 **DISCUSSION**

243 The purpose of this study was to evaluate the feasibility of performing repeated jumping in
 244 microgravity using HIFIm. We found that subjects were quickly able to master the skill of
 245 jumping in microgravity and reported that the experience of jumping in microgravity was not
 246 notably different from jumping in normal gravity. This study therefore demonstrates, for the
 247 first time, that repeated jumping using a horizontal jump sled is a realistic possibility as a future
 248 exercise countermeasure. In addition, the subjects who took part in this study represented a
 249 diverse range of users, which suggests that HIFIm potentially has wide utility. Notably, one of

250 the subjects in this study was a lower limb amputee, who was also able to exercise effectively
251 on HIFIm. This suggests that HIFIm could equally be a potent countermeasure for use in ESA's
252 para-astronaut project.

253 In this study we also tested the hypothesis that the HIFIm design would be able to minimise
254 the force transmission between the jump sled and the aircraft. This hypothesis was supported
255 as force transmission was generally negligible in microgravity apart from a consistent spike in
256 the force between HIFIm and the aircraft when the user first landed on the force plate that was
257 of a magnitude of approximately 500N (Figure 3). It is highly likely that the engineering of
258 HIFIm can be further optimised to also bring this impact spike down to negligible levels. Future
259 work is needed to understand the degree to which this force transmission is sensitive to the
260 distribution of mass within HIFIm, the direction of propulsive forces during jumping and the
261 fixation of HIFIm to the aircraft.

262 The mean peak eGRF seen in this study for normal jumping were typically between 600 and
263 1000N and were generally greater when spring resistance was increased (Figure 2). These
264 forces are considerably lower than those that were reported as being seen during the operation
265 of the jump sled used in the ESA long-term bed-rest study [6,14]. In particular, Kramer and
266 colleagues [14] reported that sled jumping forces resulted in a peak GRF that was
267 approximately 79% of the magnitude seen in normal vertical jumping – i.e. around 2750N.
268 However, it is important to note that the participants in the Kramer study were given the
269 instruction to jump as stiffly as possible, minimising the ground contact time. This is a very
270 different style of jumping to that used in the majority of the parabolas in this study. Notably,
271 we did ask participants to jump in a more similar style to that used in Kramer's study for two
272 parabolas of the final set. We found that this style of jumping produced considerably greater
273 eGRFs than were seen in the first two sets, and that this increase was seen despite the fact that

274 the lowest spring resistance was used for this set. For instance, the mean peak eGRFs seen for
275 normal jumping in set 3 were between 300 and 800N but were 1000 to 1200N for the stiffer
276 rebounding style (Figure 5).

277 It thus seems likely that eGRFs that approach those seen in the Kramer study [14] could be
278 produced if the user was instructed to produce as stiff a contact as possible against the
279 maximum spring resistance. However, the question remains as to whether this is the appropriate
280 way to use HIFIm. It is true that the protocol used in the ESA bed-rest study was highly
281 successful in mitigating the deconditioning effect of bed-rest, and that this effect was seen
282 when using the Kramer jump sled. However, the training protocol in that study comprised both
283 stiff and normal jumps and so it is impossible to know if one or other of the jumps were more
284 effective. The wider issue is that it is largely unknown what type of loading produces the
285 greatest osteogenic response. The state of the art within the literature is to calculate the
286 osteogenic index of exercise which is based upon the peak GRF and the number of impacts
287 [17]. However, it is well established that the actual stimulus to osteogenesis is dynamic strain
288 of the bone [18]. The formula for the osteogenic index is based upon the implicit assumption
289 that there is a linear relationship between the peak GRF and the strain of the affected bones.
290 Because the direct measurement of bone strains is highly invasive, there is a dearth of material
291 that have explored the relationship between peak GRF and bone strain. However, it has been
292 suggested that humans adjust their movement strategy to keep peak strains below a threshold
293 level even during vigorous activity [19]. For instance, Milgrom and colleagues [20] found that
294 there were no differences in the strain experienced when performing drop jumps from 26, 39
295 and 52 cm and that the strain experienced in the highest drop jumps was similar to that
296 experienced when running at 17 km/h. The peak GRF is just one of the variables that are
297 important in influencing the peak strain and thus much more research is needed to determine

298 the optimal loading parameters required to induce an osteogenic response. Once this is known,
299 it seems likely that exercise on HIFIm can be optimised to provide this stimulus.

300 We found that the activation of the quadriceps and gastrocnemius muscle groups was very high
301 during exercise on HIFIm – often over 100% of MVC – and the activity of the glutes was
302 moderate. Taken as a whole, this indicates that the exercise was of considerable intensity, with
303 substantial tension being generated within the prime movers. Intensity and time under tension
304 are key factors which affect the development of both muscle strength and hypertrophy [21],
305 and so these results also suggest that jumping exercise on HIFIm is also likely to be effective
306 for maintaining muscle strength and mass, as well as other connective tissues.

307 Two clear potential limitations of this work are the small subject numbers and the
308 heterogeneous nature of the sample, both of which compromise the statistical power of the
309 study. Clearly, parabolic flights represent an expensive experimental platform and so the
310 number of parabolas available for testing were limited as were the number of seats available to
311 us on each flight. Taken together these factors constrained the sample size. As the principal
312 aim of this study was to establish the feasibility of repeated horizontal jumping as an exercise
313 countermeasure we chose to recruit a heterogeneous sample in order to demonstrate that a
314 diverse range of people could use HIFIm in microgravity. Between 1998 and 2013, the age of
315 male astronauts to the ISS was between 34 and 60 years and the age of female astronauts was
316 between 30 and 56 years [22], thus the ages of the subjects in this study (male: 35, 51 and 52
317 years; female 30 and 35 years) are representative of a typical astronaut cohort. Equally, given
318 ESA's intention to explore the feasibility of para-astronauts, future missions to low earth orbit
319 may require exercise countermeasures that can be used by para-astronauts. This was the
320 rationale for including an amputee among our test users.

321 The work reported in this study has both qualified the HIFIm exercise device to a Technology
322 Readiness Level of 6 and repeated horizontal jumping to a Countermeasure Readiness Level
323 of 7. In addition, although this study has focused on the use of HIFIm to perform repeated
324 horizontal jumping it should be noted that HIFIm is a very flexible multi-modal exercise
325 device. HIFIm can be used to perform a wide range of upper and lower body exercises, and has
326 been designed to provide a varied range of stresses to the structures of the musculoskeletal
327 system that are particularly prone to deconditioning. The combination of these factors make
328 HIFIm a leading candidate to replace the Advanced Resistive Exercise Device (ARED) which
329 has been in service since 2009. In addition, ESA have shown that short bouts of intense jumping
330 activity are also effective in maintaining measures of cardiovascular fitness during long-term
331 bed-rest [6] and thus HIFIm has the potential to also replace the T2 Combined Operational
332 Load Bearing External Resistance Treadmill (COLBERT) and the Cycle Ergometer with
333 Vibration Isolation and Stabilization System (CEVIS). The prospect of replacing three exercise
334 machines with one all-purpose device is a clear advantage of HIFIm.

335 In summary, this work shows that repeated horizontal jumping is possible in microgravity using
336 the HIFIm jump sled. These results also provide proof of concept for the HIFIm engineering
337 approach, and suggest that force transmission can be minimised by this design. This work is an
338 important step forward in the realisation of repeated jumping as an exercise countermeasure.
339 Future work is needed to understand the key loading parameters that produce the optimal
340 osteogenic response such that exercise on HIFIm can be optimised accordingly.

341 **ACKNOWLEDGMENTS**

342 Special thanks to Libby Jackson, Jon Scott, Dave Green and Nora Petersen for their wisdom
343 and advice during this project. We would also like to thank CNES for the provision of an earlier
344 Parabolic Flight Campaign.

345 **FUNDING AND CONFLICTS OF INTEREST**

346 This work was supported by the UK Space Agency (grants: ST/W002248/1, ST/V002996/1
347 and ETD007) and the experimental platform was provided by ESA.

348 John Kennett is the inventor of the HIFIm jump sled that was used in this work.

349 **DATA AVAILABILITY STATEMENT**

350 The data described in this study is available on the Open Science Framework website:

351 <https://osf.io/mcdx6/>

352 doi: 10.17605/OSF.IO/MCDX6

353

354

355

356 **REFERENCES**

- 357 1 Narici MV, de Boer MD. Disuse of the musculo-skeletal system in space and on earth. *Eur*
358 *J Appl Physiol* 2011;**111**:403–20. doi:10.1007/s00421-010-1556-x
- 359 2 Rittweger J, Albracht K, Flück M, *et al.* Sarcolab pilot study into skeletal muscle’s
360 adaptation to long-term spaceflight. *NPJ Microgravity* 2018;**4**:18. doi:10.1038/s41526-
361 018-0052-1
- 362 3 Sibonga JD, Spector ER, Johnston SL, *et al.* Evaluating Bone Loss in ISS Astronauts.
363 *Aerosp Med Hum Perform* 2015;**86**:A38–44. doi:10.3357/AMHP.EC06.2015
- 364 4 Moore AD, Downs ME, Lee SMC, *et al.* Peak exercise oxygen uptake during and
365 following long-duration spaceflight. *APSselect* 2014;**1**:231–8.
366 doi:10.1152/jappphysiol.01251.2013@apsselect.2014.1.issue-9
- 367 5 Petersen N, Jaekel P, Rosenberger A, *et al.* Exercise in space: the European Space Agency
368 approach to in-flight exercise countermeasures for long-duration missions on ISS. *Extreme*
369 *Physiol Med* 2016;**5**:9. doi:10.1186/s13728-016-0050-4
- 370 6 Kramer A, Gollhofer A, Armbrrecht G, *et al.* How to prevent the detrimental effects of two
371 months of bed-rest on muscle, bone and cardiovascular system: an RCT. *Sci Rep*
372 2017;**7**:13177. doi:10.1038/s41598-017-13659-8
- 373 7 Kramer A, Kümmel J, Mulder E, *et al.* High-Intensity Jump Training Is Tolerated during
374 60 Days of Bed Rest and Is Very Effective in Preserving Leg Power and Lean Body Mass:
375 An Overview of the Cologne RSL Study. *PloS One* 2017;**12**:e0169793.
376 doi:10.1371/journal.pone.0169793
- 377 8 Ritzmann R, Freyler K, Kümmel J, *et al.* High Intensity Jump Exercise Preserves Posture
378 Control, Gait, and Functional Mobility During 60 Days of Bed-Rest: An RCT Including 90
379 Days of Follow-Up. *Front Physiol* 2018;**9**:1713. doi:10.3389/fphys.2018.01713
- 380 9 Kohrt WM, Barry DW, Schwartz RS. Muscle Forces or Gravity: What Predominates
381 Mechanical Loading on Bone? *Med Sci Sports Exerc* 2009;**41**:2050–5.
382 doi:10.1249/MSS.0b013e3181a8c717
- 383 10 O’Bryan SJ, Giuliano C, Woessner MN, *et al.* Progressive Resistance Training for
384 Concomitant Increases in Muscle Strength and Bone Mineral Density in Older Adults: A
385 Systematic Review and Meta-Analysis. *Sports Med Auckl NZ* Published Online First: 24
386 May 2022. doi:10.1007/s40279-022-01675-2
- 387 11 Layne JE, Nelson ME. The effects of progressive resistance training on bone density:
388 a review. / Effets d’un entraînement progressif de musculation sur la densité osseuse:
389 revue. *Med Sci Sports Exerc* 1999;**31**:25–30.
- 390 12 Suchomel TJ, Nimphius S, Bellon CR, *et al.* The Importance of Muscular Strength:
391 Training Considerations. *Sports Med Auckl NZ* 2018;**48**:765–85. doi:10.1007/s40279-018-
392 0862-z

- 393 13 Schoenfeld BJ, Grgic J, Ogborn D, *et al.* Strength and Hypertrophy Adaptations
394 Between Low- vs. High-Load Resistance Training: A Systematic Review and Meta-
395 analysis. *J Strength Cond Res* 2017;**31**:3508–23. doi:10.1519/JSC.0000000000002200
- 396 14 Kramer A, Ritzmann R, Gollhofer A, *et al.* A new sledge jump system that allows
397 almost natural reactive jumps. *J Biomech* 2010;**43**:2672–7.
398 doi:10.1016/j.jbiomech.2010.06.027
- 399 15 Cushion EJ, Warmenhoven J, North JS, *et al.* Principal Component Analysis Reveals
400 the Proximal to Distal Pattern in Vertical Jumping Is Governed by Two Functional
401 Degrees of Freedom. *Front Bioeng Biotechnol* 2019;**7**. doi:10.3389/fbioe.2019.00193
- 402 16 Price PDB, Gissane C, Cleather DJ. Reliability and minimal detectable change values
403 for predictions of knee forces during gait and stair ascent derived from the FreeBody
404 musculoskeletal model of the lower limb. *Front Bioeng Biotechnol* 2017;**5**:74.
405 doi:10.3389/fbioe.2017.00074
- 406 17 Turner CH, Robling AG. Designing Exercise Regimens to Increase Bone Strength.
407 *Exerc Sport Sci Rev* 2003;**31**:45–50.
- 408 18 Turner CH. Three rules for bone adaptation to mechanical stimuli. *Bone*
409 1998;**23**:399–407. doi:10.1016/S8756-3282(98)00118-5
- 410 19 Burr DB. In vivo measurement of human tibial strains during vigorous activity. *Bone*
411 1996;**18**:405–10.
- 412 20 Milgrom C, Finestone A, Levi Y, *et al.* Do high impact exercises produce higher tibial
413 strains than running? *Br. J. SPORTS Med.* 2000;**34**:195–9. doi:10.1136/bjism.34.3.195
- 414 21 Borde R, Hortobágyi T, Granacher U. Dose-Response Relationships of Resistance
415 Training in Healthy Old Adults: A Systematic Review and Meta-Analysis. *Sports Med*
416 *Auckl NZ* 2015;**45**:1693–720. doi:10.1007/s40279-015-0385-9
- 417 22 Goel N, Bale T, Epperson C, *et al.* Effects of Sex and Gender on Adaptation to Space:
418 Behavioral Health. *J Womens Health* 2002 2014;**23**. doi:10.1089/jwh.2014.4911

419

420